Vector[™] V200 GNSS Compass

General Navigation Heading and Positioning Compass



- L1 GPS, GLONASS, Galileo, BeiDou, QZSS
- 30 cm RMS world-wide positioning accuracy with Atlas corrections
- 0.75 degree heading accuracy in an amazingly small form factor
- Excellent in-band and out-of-band interference rejection
- Integrated gyro and tilt sensors help deliver fast start-up times and provide heading updates during temporary loss of satellites
- Provides heading, positioning, heave, roll, and pitch

Experience superior navigation from the accurate heading and positioning performance available with the Vector™ V200 GNSS compass. The multi-GNSS Vector V200 supports GPS, GLONASS, BeiDou, Galileo, and QZSS and offers an amazing world-wide 30 cm (RMS) accuracy via Hemisphere's Atlas GNSS global correction service.

The Vector V200 offers an incredible combination of simple installation, small form factor, and amazing performance. The compass - measuring only 35 cm in length - mounts easily to a flat surface or pole. The stability and maintenance-free design of the Vector V200 provides simple integration into autopilots, chart plotters, and AIS systems.



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Vector V200 GNSS Compass

GNSS Sensor Specifications

Receiver Type: Vector GNSS L1 Receiver

Signals Received: GPS, GLONASS, BeiDou, Galileo, QZSS 7, and

Atlas Channels: 424 -142 dBm

GPS Sensitivity: SBAS Tracking: 2-channel, parallel trackina Update Rate: 10 Hz standard, 20 Hz optional

Timing (1PPS)

20 ns 6 Accuracy:

Rate of Turn: 100°/s maximum

Compass Safe 50 cm 4 Distance:

Cold Start: 60 s (no almanac or RTC) Warm Start:

30 s typical (almanac and RTC)
10 s typical (almanac, RTC and position)
10 s typical (valid position)
1,850 mph (999 kts) Hot Start: Heading Fix:

Maximum Speed: 18,288 m (60,000 ft) Maximum Altitude: Differential Options: SBAS, Atlas (L-band)

Accuracy

Positioning: Default (RMS) Optional (RMS)

Autonomous, no SA:1 1.5 m SBAS: 2 $0.5 \, \mathrm{m}$ $0.3 \, \mathrm{m}$ Atlas (L-band): 6 $0.3 \, \mathrm{m}$ Heading (RMS): 0.75° 1.5° Pitch/Roll (RMS):

Heave (RMS): 30 cm ³

L-Band Receiver Specifications

Receiver Type: Single Channel 1525 to 1560 MHz Channels:

Sensitivity: -130 dBm Channel Spacing: 5 kHz

Satellite Selection: Manual or Automatic Reacquisition Time: 15 sec (typical)

Communications

Ports:

5-pin 12-pin NMEA2000 or RS-232 (1 Tx, 1 Rx) RS-232 (2 Tx, 2 Rx), RS-422 (1 Tx), 1PPS or RS-422 (2 Tx, 1 Rx), 1PPS

RTCM SC-104

4800 - 115200

Baud Rates: Correction I/O Protocol:

Data I/O Protocol:

NMEA 0183, NMEA 2000, Crescent binary 5 5-pin

12-pin NMEA 0183, Crescent binary 5

Timing Output: 1PPS (CMOS, rising edge sync 6)

SBAS

Atlas

Input Voltage: 6 to 36 VDC

Power Consumption: (multi-GNSS, typical continuous draw @

3.6 W Atlas

Current Consumption: (multi-GNSS, typical continuous draw

@ 12V) 0.30 A 0.33 A

Power Isolation: Isolated to enclosure

Reverse Polarity Protection: Yes

Environmental

-40°C to + 70°C (-40°F to + 158°F) Operating Temperature: Storage Temperature: -40°C to +85°C (-40°F to + 185°F)

95% non-condensing Humidity:

Enclosure: ISO 60529:2013 for IPx6/IPx7/IPx9 Vibration: IEC 60945:2002 Section 8.7 Vibration EMC:

EN 303 413 V1.1.1

IEC60945:2002 EN 301 489-1 V2.1.1 EN 301 489-5 V2.1.1 EN 301 489-19 V2.1.0

Mechanical

Dimensions: No Mount: 34.8 L x 15.8 W x 7.5 H (cm) LP Flat Mount: 34.8 L x 15.8 W x 7.6 H (cm) HP Flat Mount: 34.8 L x 15.8 W x 10.7 H (cm) Pole Mount: 34.8 L x 15.8 W x 16.8 H (cm)

Weight:

Not including Mount: 0.75 kg (1.7 lb) Including Mount: 0.94 kg (2.1 lb) Power/Data Connector: 5-pin or 12-pin

Aiding Devices

Gyro:

Tilt Sensors:

Provides smooth heading, fast heading reacquisition and reliable 1° per minute heading for periods up to 3 minutes when loss of GPS has occurred 4 Provide pitch and roll data and assist in fast start-up and reacquisition of heading solution

1 Depends on multipath environment, number of satellites in view, satellite geometry, no SA, and ionospheric activity

- 2 Depends on multipath environment, number of satellites in view, WAAS coverage and satellite aeometry
- 3 Based on a 40 second time constant
- 4 This is the minimum safe distance measured when the product is placed in the vicinity of the steering magnetic compass. The ISO 694 defines "vicinity" relative to the compass as within 5 m (16.4 ft) separation
- 5 Hemisphere GNSS proprietary
- 6 V200s only
- 7 With future firmware upgrade and activation

Authorized Distributor:

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