

## **TOTAL STATION SPECIFICATIONS**

Model			R-2501NS	R-2502NS	R-2503NS	R-2505NS
Telescope	Magnification			30X		
	Effective Aperture		45mm (EDM45mm)			
	Resolving Power			3"	•	
	Field of View			1°30′ (2.	6%)	
	Minimum Focus			1.0 n		
Distance Measurement	Laser Class			Laser Pointer: Class 2, Whe		
	Measurement Range Good Conditions *3				g	
		Reflectorless *1		0.5m ~ 6	00m	
		Reflector Sheet *2		1.5m ~ 600		
		1P		1.5m ~ 7000		
		3P		1.5m ~ 9000		
	Mini Prism			1.5m ~ 2500 (3000) m		
	Measurement Accuracy *4				,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,	
	Reflectorless 0.5 ~ 100m			±(3+2ppm>	KD) mm	
	100 ~ 300m			±(5+2ppm×D) mm		
	300m ~			±(7+2ppm×D) mm		
	Prism /Reflector Sheet *5			±(2+2ppm)		
	Minimum Count			Normal Meas.: 1 mm or 0.1	·	
	Measurement Time	*5				
	Initial Meas.	Reflectorless		Approx. 1.0 sec.		
		Prism/Refl. Sheet		Approx. 1.2 sec.		
	Continuous Meas.	Reflectorless		Approx. 0.8 sec.		
		Prism/Refl. Sheet		Approx. 0.8 sec.		
	Weather Correlation		Auto, Temp., Pr		Temp., Press	ure Input
			/PPM No-Inpu	·	/PPM No-Inpu	•
	Laser Pointer		,	Yes		
Angle Measurement	Measuring Method			Absolute Rotary Encoder		
	Detection Method			H: 2 Sides Detection V: 2 Sides Detection		
	Minimum Count			5"/1" Selectable		
	Accuracy (ISO 17123	-3)	1 "	2 "	3"	5 "
	Tangent Screw		2 Spe	ed	1 Spe	ed
Display Type			2 Sides with Illumination			
Compensator *7	Compensator Type		Float Type Level Capacitance		Type Level	
	Compensator Axis		3 Ax	is	2 Ax	is
	Compensator Range			±3	i	
Special Function	Measurement/Calculation		File Managemen	File Management, Measure, View & Edit, Free Station, Stakeout, Traverse, VPN, I/C		
				Preference, Load Design, PegSurvey (Mining Software		
Data Process	Data Recording Method			Internal Memo	ry/SD Card	
	Capacity (Coordinates/Observation Data) *8			Approx. 60,00	00 points	
nterface				SD Card Slot, Mini USB Port,	RS-232C, Bluetooth Class 2	
Sensitivity of Vials	Electrical Level		30"/1	div.	N/A	١
	Circular Level			8 "/2 mm		
aser Plummet				Brightness and Optical Axis Adjustable		
Base				Detachable		
oust & Water Protection				IP56 (instrument only)		
perating Temperature Range				-20 °C ~ +50 °C		
Dimensions				190 (W) x 343 (H) x 177 (L) mm		
Veight (incl. Battery)				5.7 k	g	
Battery Pack (BP07)	Power Source		Li-io	n 7.4V 3350mAh, equipped with	2 batteries as standard, Hot-Sv	vappable
	Operation Time/Charge					
	Continous Meas.			Approx 15 hrs. (N	Measured once every 30 sec.) *6	5
	Angle Meas.		Approx. 47.5 hrs.			
	Charging Time		1 battery: approx. 2 hrs. / When charging 2 batteries at the same time: approx. 4 hrs.			hrs.

- \*1 The measurement range and accuracy of reflectorless, and time required to measure may vary by the shape, size of surface area and reflection rate of the target and its environment. The measurement range of reflectorless is determined by the white side of the KODAK Gray Card (KODAK is a registered trademark of Eastman Kodak Company). Reflector sheet: based on PENTAX Genuine Reflector sheet.
- \*3 Normal or good weather conditions are based on the following conditions.
- Normal conditions: 20km visibility with slight shimmer, weak sunlight and moderate wind.
- \*4 During the automatic weather correction, the value of ppm error is 10ppm in case of the prism or reflector sheet measurement. Also in case of the reflectorless measurement, it will be 18ppm depending on the distance (300m or more) and change in environmental conditions, shape, area and reflectance of targets.

  EDM measuring time is determined in good conditions. It may takes longer than usual to measure the distance exceeding
- 4000m in prism mode and 300m in reflectorless mode.
- When EDM energy saving setting is "Yes".
- The 3-axis correction is a function to correct the orthogonal error between the horizontal axis and the collimation axis and the orthogonal error between the vertical axis and the horizontal axis in addition to the XY 2-axis correction.
- The number of recorded points varies depending on the observation method and it is the number of observed points when the coordinate, one pair of observation and pairs of observation are used separately, but not combination of each of them. The pairs of observation is a typical number of observation points in the case of one pair of five-direction observation. Maximum number of recorded points in one site: 3,000 points Maximum number of sites created: 20 sites Maximum number of data transfer points from personal computer to total station 1,000 points.

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